

## Lecture 10: Linear maps

Last time: Dimension of a vector space

### Def. 3.2 | Linear maps

Let  $V, W$  be vector spaces over a field  $\mathbb{F}$ . A linear map

$T: V \rightarrow W$  is a function satisfying:

- .)  $T(x+y) = T(x) + T(y)$  for all  $x, y \in V$
- .)  $T(\alpha \cdot x) = \alpha T(x)$  for all  $\alpha \in \mathbb{F}, x \in V$ .

The set of all linear maps from  $V$  to  $W$  is denoted

$$\mathcal{L}(V, W) = \mathcal{L}_{\mathbb{F}}(V, W).$$

Sometimes we also write  $Tv = T(v)$  for  $T \in \mathcal{L}(V, W), v \in V$ .

### Examples of linear maps:

- .) Identity map  $I: V \rightarrow V, Iv = v$  for all  $v \in V$ ,
- .) Zero map  $O: V \rightarrow W, Ov = 0_W$  for all  $v \in V$ .
- .) Reflections, rotations, projections, differentiation (see Lecture 1)

.) Fundamental example: Let  $m, n \in \mathbb{N}$ , and  $A = (A_{ij})_{i,j}$ ,

$A_{ij} \in \mathbb{F}$  for  $1 \leq i \leq m, 1 \leq j \leq n$ .

$$T_A : \mathbb{F}^n \rightarrow \mathbb{F}^m, \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \mapsto y = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix}, \quad y_i = \sum_{j=1}^n A_{ij} x_j$$

We will prove later: Every linear map essentially looks like this.

Prop 3.11 Every linear map  $T: V \rightarrow W$  satisfies  $T(0_V) = 0_W$ .

Proof: We have  $0 = 0 + 0$ , and hence

$$T(0) = T(0+0) = T(0) + T(0) \Rightarrow T(0_V) = 0_W. \quad \square$$

A linear map is uniquely defined on a basis:

Prop 3.5 Let  $\{v_1, \dots, v_n\}$  be a basis of  $V$ , and let  $w_1, \dots, w_n \in W$  be arbitrary. Then there exists a unique linear map  $T: V \rightarrow W$  with  $T(v_j) = w_j$  for all  $1 \leq j \leq n$ .

Proof:  $\rightarrow$  Existence: Define a map  $\bar{T}: V \rightarrow W$  via  $\bar{T}(v_j) = w_j \forall j$ , and extend it linearly to the whole space:

$$\text{for } v \in V, \quad v = \sum_{j=1}^n a_j v_j \quad (\{v_i\}_i \text{ are a basis of } V),$$

$$\bar{T}(v) = \bar{T}\left(\sum_{j=1}^n a_j v_j\right) := \sum_{j=1}^n a_j \bar{T}(v_j) = \sum_{j=1}^n a_j w_j$$

This is a linear map by definition, and it is well-defined, because the coefficients  $a_j \in \mathbb{F}$  in  $v = \sum_{j=1}^n a_j v_j$  are unique, and if  $v=w$ , then  $v-w=0$ , and (Prop 2.29)

$$0 = T(0) = T(v-w) = T(v) - T(w) \Rightarrow T(v) = T(w).$$

Props 3.11

$\Rightarrow$  Uniqueness: Let  $S$  be another linear map  $V \rightarrow W$  with  $S(v_j) = w_j$ . Then

Let  $v = \sum_{j=1}^n a_j v_j \in V$  be arbitrary, then

$$\begin{aligned} T(v) &= T\left(\sum_{j=1}^n a_j v_j\right) = \sum_{j=1}^n a_j T(v_j) = \sum_{j=1}^n a_j w_j = \sum_{j=1}^n a_j S(v_j) \\ &= S\left(\sum_{j=1}^n a_j v_j\right) = S(v) \end{aligned}$$

$\Rightarrow$  since  $v$  was arbitrary,  $T=S$ .  $\square$

The set of all linear maps  $\mathcal{L}(V, W)$  is itself a vector space:

Props 3.6 / 3.7

Define addition and scalar multiplication in  $\mathcal{L}(V, W)$  point-wise:

$\cdot$ )  $S, T \in \mathcal{L}(V, W) : S + T : v \mapsto S(v) + T(v)$

$\cdot$ )  $a \in \mathbb{F}, T \in \mathcal{L}(V, W) : aT : v \mapsto aT(v)$

(HW:  $S+T, aT \in \mathcal{L}(V, W)$ ) Then  $(\mathcal{L}_{\mathbb{F}}(V, W), +, \cdot)$  is a VS over  $\mathbb{F}$ .

Proof: Easy exercise (neutral element for +: zero map  $0: v \mapsto 0_v$ ). □

We can also compose / "multiply" linear maps:

**Def 3.8** Let  $T \in L_{\mathbb{F}}(U, V)$  and  $S \in L_{\mathbb{F}}(V, W)$ ,

then the map  $S \circ T = ST: U \rightarrow W$ , defined by

$$(ST)(u) = S(T(u)) \quad \text{for } u \in U,$$

is again a linear map:

$$\begin{aligned} \Rightarrow (ST)(x+y) &= S(T(x+y)) = S(T(x)+T(y)) \\ &= S(T(x))+S(T(y)) \\ &= (ST)(x)+(ST)(y) \quad \forall x, y \in U \end{aligned}$$

$$\begin{aligned} \Rightarrow (ST)(ax) &= S(T(ax)) = S(aT(x)) \\ &= a[S(T(x))] = a(ST)(x) \quad \forall a \in \mathbb{F} \\ &\qquad \qquad \qquad x \in U \end{aligned}$$

Prop 3.9

Properties of the product of linear maps

i) Associativity:  $(RS)\bar{T} = R(S\bar{T})$  for  $\bar{T} \in \mathcal{L}(V_1, V_2)$

$$S \in \mathcal{L}(V_2, V_3)$$

$$R \in \mathcal{L}(V_3, V_4)$$

ii) neutral element:  $\bar{T} I_V = I_W \bar{T}$  for all  $\bar{T} \in \mathcal{L}(V, W)$

$$(I_x : X \rightarrow X \text{ identity map})$$

iii) Distributive laws:  $(Q+R)S = QS + RS$   $Q, R \in \mathcal{L}(U, V)$

$$Q(S+\bar{T}) = QS + QT \quad S, \bar{T} \in \mathcal{L}(U, V)$$

Proof: i)  $x \in V_1$ :  $[(RS)\bar{T}](x) = (RS)(\bar{T}(x))$

$$= R(S(\bar{T}(x)))$$

$$= R(S\bar{T}(x))$$

$$= [R(S\bar{T})](x) \Rightarrow (RS)\bar{T} = R(S\bar{T}).$$

ii)  $x \in V$ :  $(\bar{T} I_V)(x) = \bar{T}(I_V(x)) = \bar{T}(x) = I_W(\bar{T}(x)) = (I_W \bar{T})(x)$

$$\Rightarrow \bar{T} I_V = I_W \bar{T}.$$

iii)  $H\omega$

□